

## City of Oregon City

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## **Legislation Text**

File #: PC 17-136, Version: 1

LE 17-02 Legislative Amendment to Adopt the McLoughlin-Canemah Trail Plan, Amending the Transportation System Plan, Trails Master Plan, and Parks Master Plan

## **RECOMMENDED ACTION (Motion):**

Staff recommends that the Planning Commission accept testimony and recommend approval of file LE 17-02 to the City Commission.

## **BACKGROUND:**

The applicant proposed to update and amend the Oregon City Transportation System Plan (2013), the Parks Master Plan (2008), and Trails Master Plan (2004) by adopting the McLoughlin-Canemah Trail Plan. These plans are Ancillary Documents to the Oregon City Comprehensive Plan. These plans envision a trail connection between McLoughlin Promenade and Old Canemah Park, with links to Canemah Children's Park through the Canemah Historic District. The McLoughlin-Canemah Trail Plan is a concept plan that would refine the existing projects identified in the Transportation, Trails, and Parks plans.

In 2016, the City of Oregon City, in partnership with the Oregon City Trail Alliance, the McLoughlin Neighborhood Association, and the Clackamas County Historical Society, was granted a Nature in Neighborhoods grant of \$25,000 to fund a planning effort for the McLoughlin-Canemah Trail (MCT), a segment of the larger Oregon City Loop Trail. The objective of the grant-funded trail plan project was to determine an alignment for a permanent trail, and to identify an interim trail alignment and safety upgrades.

Three trail alignments were considered by an appointed Community Advisory Group. The group's recommendation includes an interim and long term permanent trail alignment. Full details are available in the attached report: McLoughlin-Canemah Trail Plan: Alignment Feasibility and Evaluation Report.

The plan has been slightly revised after additional meetings and decisions by the Advisory Group subsequent to the first Planning Commission hearing in November 2017. These changes are described in the attached Issues matrix.